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# M.Sc. (Electronics) (Sem - I) (New) (NEP CBCS) Examination:

			March/April Advanced Microcont			
_			hursday, 15-May-2025 M To 05:30 PM		Max. Marks:	60
Insti	ructio	ns:	<ol> <li>All questions are compulsory</li> <li>Figure to the right indicate for</li> </ol>		arks.	
Q.1	A)		oose correct alternative. In PIC16F877 instruction a) RETLW c) RETFIE	b)	sed to return from a subroutine. RETURN GOTO	80
		2)	In ATmega8L to perform a bitwinstruction is used. a) OR c) AND	b)	AND operation in AVR  XOR ADD	
		3)	instruction is used to sub- PIC16F877. a) SUBWF c) DECFSZ	b)	WREG from a file register in ADDWF INCFSZ	
		4)	In AVR ATmega8L general g		urpose registers are available. 24 64	
		5)	The resolution of the ADC in A a) 8-bit c) 12-bit	b)	10-bit	
		6)	<ul> <li>instruction set does AVR</li> <li>a) Complex Instruction Set Co</li> <li>b) Reduced Instruction Set Co</li> <li>c) Very Long Instruction Word</li> <li>d) Micro coded Instruction Se</li> </ul>	uter (CISC) uter (RISC)		
		7)	<ul><li>port is used as the analog</li><li>a) PORTA</li><li>c) PORTC</li></ul>	g inp b) d)	ut in PIC16F877. PORTB PORTD	
		8)	The PIC16F877 package have a) 28 c) 44	b) d)	_ pins. 40 20	

	B)	<ol> <li>State true or false.</li> <li>ATmega8L supports a total of 3 external interrupts.</li> <li>In the PIC16F877, the WDT (Watchdog Timer) is disabled by default.</li> <li>AVR ATmega8L has an internal EEPROM with a size of 512 bytes.</li> <li>The maximum operating clock frequency of the PIC16F877 is 40 MHz.</li> </ol>	04
Q.2	Ans a) b) c) d) e) f) g) h)	Write any four features of PIC microcontroller. List the different types of Temperature sensors. Write note on watchdog timer of AVR microcontroller. List the Steps of AVR Studio programming. Write note on Status register of PIC microcontroller. Compare AVR and PIC microcontroller. Write note on Flash program memory of AVR microcontroller. Draw the Opto-coupler interfacing diagram with AVR.	12
Q.3	Ansa) b) c) d)	Write note on PWM technique.  Draw the Reset and clock circuits of PIC microcontroller.  Write note on Arithmetic instruction set of AVR microcontroller.  List the Steps of Micro C the IDE for embedded C programming.	12
Q.4	Ans a) b) c)	swer the following. (Any Two)  Explain Addressing modes in Instruction set of PIC microcontroller.  Explain On chip ADC of AVR microcontroller.  Write note on universal asynchronous receiver and transmitter of AVR.	12
Q.5	Ans a) b) c)	swer the following. (Any Two) Explain Architecture of 16F877. Write a program to blink the LED array connected at port B. Explain pH Measurement embedded system using AVR in details.	12

Seat	Sat	D
No.	Set	

# M.Sc. (Electronics) (Sem - I) (New) (NEP CBCS) Examination:

				March Industrial Power	/April - 20 Electron		
•				ırday, 17-May-2025 To 05:30 PM		Max. Marks	s: 60
Inst	ructi	ions		All questions are comp Figures to the right ind		narks.	
Q.1	A)		In A and a)	se correct alternative. C voltage controller if to off for 75 cycles then to 4.0 3.0	the SCRs	are switched on for 25 cycles ycle would be  0.20 0.25	80
		2)	a)	_ provide variable outp Inverter AC voltage controllers	b)	Cycloconverter	
		3)	vary a)	-		t voltage is controlled by extinction angle All of these	
		4)	a)	Murray - Bedford invert voltage commutation class B		technique of commutation. current commutation class A	
		5)		firing angle		e is controlled by changing the width of pulses All of these	
		6)	V <sub>rms</sub> a)	unidirectional AC volta varies from  Vs to Vs/ $\sqrt{2}$ Vs to $\sqrt{2}$ . Vs	b)	ler if $\alpha$ varies from o to $\pi$ the Vs to Vs/2 None of these	
		7)		ycloconverter output is thyristors.	controlled	by controlling the of	
			-	conduction angle Width	b) d)	Phase delay angle	

	8)		hoppers, for chopping petrolled by varying	eriod T ,	the output voltage can be	
				nt b)	Toff keeping T constant	
			Ton keeping T constan			
		-,	3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3	,		
	B) 1	True c	or false:			04
		·	the output load voltage frequency f with ton cor Cycloconverters provid Thyristors of AC voltage commutation circuitry.	e V <sub>Lav</sub> ca nstant. de outpu ge contro	t with fixed frequency.	
Q.2	Answ	er the	e following (Any Six).			12
	a)		the applications of rectif			
	b)		t do you mean by the ha ion the methods used fo		in the cycloconverter circuit?	
	c)		uss the role of free whee			
	ď)	What	t are the choppers? Clas	ssify the		
	•		the applications of inver		_	
	-		the diagram of class B t the advantages of cycl			
	h)	Bidire			firing angle greater than pf	
Q.3	Answ	er the	e following (Any Three	)		12
4.0				-	ollers and cycloconverters.	
		Desc			unidirectional controllers with	
	-	•	ain the operation of SAC	•		
	d)		a neat labeled diagram oconverter.	for thre	e phases to single phase	
Q.4	Answ	er the	e following (Any Two).			12
	a)	With			ing of single-phase dual	
	p)		uss the working of step u			
	c)	Desc	ribe the working of singl	e-phase	e bridge inverter.	
Q.5			e following (Any Two).			12
	a)				Murray full bridge inverter.	
	b)		cribe the operation of sin cribe the operation of thre	-	se half wave controllers. e dual converter	
	٥,	2000	and operation of this	oo pilao	o addi com com	

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# M.Sc. (Electronics) (Sem - I) (New) (NEP CBCS) Examination:

				Marc Numerical	h/April Method			
•				nday, 19-May-2025 To 05:30 PM			M	ax. Marks: 60
Inst	ructi	ions		All questions are con ) Figures to the right ir			narks.	
Q.1	A)		Ab a) b) c)	solute error (e <sub>a</sub> ) =  Actual value - appro  True value - approxi  Absolute error /  true  None of the mentione	ximate val mate val value		-	08
		2)	a)	the least square methe normal equations general equations	b	se <u>.</u> )	to find the value regression equations auxiliary equations	of unknowns.
		3)		Decomposition methors Tangularization methors both a) and b)	nod b		nown as LU Factorization metl none of the mentione	
		4)	a) b) c) d)	interpolation technic Newtons forward diff Newtons backward d Stirling's interpolation All of the mentioned	erences lifference	inte s ir	erpolation method	nces
		5)	ma a)	e LU method of factor athematician Alan Tango G. W. Leibniz		)	introduced by the David Hilbert Alex Grothendieck	
		6)	a)	$f(t) = t \sin(at)$ then its $\sqrt{\pi/2}\sqrt{s}$ Indeterminate	b	)	ransform $f(t)$ is $a/s^2 + a^2$ $2as/(s^2 + a^2)^2$	
		7)		Approximates $f(x)$ b Approximates $f(x)$ b Approximates $f(x)$ b Approximates $f(x)$ b	y parabo y a 3 <sup>rd</sup> oı	de	• •	

d) None of the mentioned

- 8) The voltage across the LC combination in a series RLC circuit is \_\_\_\_\_ a) 0 b) c) 2 d) 3 B) State true or false: 04 a) The coefficients of the equation obtained during the elimination called Pivots. b) The Laplace transform of impulse function is 1/s. c)  $B^{-1}AX = A^{-1}B$  the solution of system of equation in form of AX = Bd) Unit of inductance is Henry. 12 Q.2 Answer the following (Any Six). Write a note on curve fitting. Compute the value of the  $I = \int_0^1 e^{-x} dx$  by using trapezoidal rule. b) What is backward substitution method? c) d) Write cubic spline interpolation formula. e) What is Euler's method? What is Inverse Laplace transform? f) Define matrix. Write types of matrices. What are the different types of RK method? h) Q.3 Answer the following (Any Three) 12 Find out the tridiagonal matrix for R-2R ladder network in numerical analysis. Write a note on Eigen values and vector. b) Prove that  $L\{f'''(t)\} = s^3f(s) - s^2f(0) - sf'(0) - f''(0)$ Explain Runge Kutta method. Q.4 Answer the following (Any Two) 12 Find a value of f(13) by using Newton's forward interpolation method. 20 10 30 40 50 Χ 1.11 3.60 1.81 2.61 4.86 У
  - b) Explain Taylor's series method.
  - Fit a curve of the form  $y = \frac{x}{ax+b}$  for the data given below by the method of least square.

Х	2	4	6	8	10
У	8.8	13.7	17.0	18.9	20.4

### Q.5 Answer the following (Any Two).

a) Using the least square fitting process fit the following data to straight line.

Х	0	1	2	3	4
У	2	4	6	8	10

- b) Solve the system of equations using Gauss elimination method
  - a)  $2x_1 + x_2 + x_3 = 10$
  - b)  $3x_1 + 2x_2 + 3x_3 = 18$
  - c)  $x_1 + 4x_2 + 9x_3 = 16$
- c) Explain Absolute error and Relative error and calculate absolute and relative errors, comment on the result.
  - i) True value =  $1 \times 10^{-6}$ , approximate value =  $0.5 \times 10^{-6}$
  - ii) True value =  $1 \times 10^6$ , approximate value =  $0.99 \times 10^6$

12

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	IVI.	March/April - 2025  Research Methodology (2313103)	
		e: Saturday, 24-May-2025 Max. Marks: 60 0 PM To 05:30 PM	)
Insti	ructio	ns: 1) All questions are compulsory. 2) Figures to the right indicate full marks.	
Q.1	•	Choose correct alternative.  A research design must contains  a) a clear statement of the research problem  b) procedures and techniques to be used for gathering information  c) the population to be studied  d) all of the mentioned	3
	2)	is called non-probability sampling.  a) Cluster sampling b) Quota sampling c) Systematic sampling d) Stratified random sampling	
	3)	Bibliography given in a research report  a) helps those interested in further research b) shows vast knowledge of the researcher c) has no relevance to research d) all the above	
	4)	Action-research is  a) An applied research  b) A research carried out to solve immediate problems  c) A longitudinal research  d) All the above	
	5)	does not correspond to characteristics of research.  a) Research is not passive b) Research is systematic c) Research is not a problem-oriented d) Research is not a process	
	6)	Formulation of hypothesis may not be required in  a) Survey method b) Historical studies c) Experimental studies d) Normative studies	

	7)	•		•		ai research is	
		,	eference colle ontrolling	ection	b) d)	Manipulation and replication Observation	
	8)	require a) Re	eptual framew before reseal esearch hypo esearch parac	ch. thesis		Stood as a that you  Synopsis of Research  Research design	
	B) 1) 2) 3) 4)	A resea indepen Survey A null hy When a	ident and deptis not the me ypothesis is wanted and the inter- research pro	pendent varial thod of Resea when there is oblem is relate	oles. arch. diffei ed to	when it consists of rence between the variables. heterogeneous population, stratified Sampling.	04
Q.2	a) b) c) d) e) f)	State 7 Define r What ar State th What is What is What is	research desi re data analys e tools in app referencing s measuremer hypothesis?	e research wgn. sis techniques lied research style?	? :he te diag	echniques of measurement?	12
Q.3	a) b) c)	Explain Distingu Write a	iish between note on litera	any Three) as of an ideal Analysis & Inture survey a s. analytical re	terpr	etation. eview.	12
Q.4	a)	Explain studies. Write a	note on Bar o	•	cha		12
Q.5	a)	Write a Explain		ctive and indo cess with flow			12

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	M	l.Sc		Ápril - 20	
-			Wednesday, 14-May-2025 AM To 01:30 PM	5	Max. Marks: 60
Inst	ructi	ons	: 1) All questions are comp 2) Figure to right indicate	•	
Q.1	A)	1)	oose correct alternative. Regenerative feedback in a) oscillations c) negative sign	mplies feedb b) d)	step input positive sign
		2)	called a  a) feedback c) signal	b) d) d)	
		3)	called a) computer control sys	stem b)	
		4)	increased	em should bem should be sto the loop	e decreased
		5)	In an open loop control s a) Output is independe b) Output is dependent c) Only system parame d) None of the above	nt of control	
		6)	Zero initial condition for a  a) input reference signa b) zero stored energy c) no initial movement d) system is at rest and	al is zero of moving p	

		7)	An automatic toaster is a loop control system. a) open b) closed c) partially closed d) any of the above	
		8)	A control system in which the control action is somehow dependent on the output is known as  a) Closed loop system b) Semi closed loop system c) Open system d) None of the above	
	B)	Sta 1) 2) 3) 4)	the True or False.  In frequency domain analysis, the frequency of input signal should vary from 0 to ∞  If damping factor ξ = 1, then the roots are imaginary and complex conjugate.  If two gain blocks G1 and G2 are in series then for block diagram reduction, it is replaced by a block of gain G1G2.  Nyquist polar plots are not suitable to express the stability of the system.	04
Q.2	Ans a) b) c) d) e) f) g) h)	Def Wri Def Wri List Def Exp	the following question (Any Six) ine Steady state error. ise note on signal flow graphs. ine PID system. ise a note on Process control system. is characteristics of PI system. ine Bode plots. lain the concept of stability. ine poles and zeros.	12
Q.3	Ans a) b) c) d)	Cor Wri Wri Sta	the following question (Any Three) npare the open loop and closed loop system. te note on Root contours. te note on PD Control system. te any two properties of Signal flow graph. Justify each with an imple.	12
Q.4	Ans a) b) c)	Exp	the following question (Any Two) lain Polar plots with suitable example. lain Routh stability criterion. npare the Block Diagram representation and Signal flow graph.	12
Q.5	Ans a) b) c)	Exp	the following question (Any Two) lain Nyquist stability criteria. lain construction of root loci. lain Effect of adding zero to the system.	12

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# M.Sc. (Electronics) (Sem - II) (New) (NEP CBCS) Examination:

	March/Apri Real Time Operating S		
•	Friday, 16-May-2025 M To 01:30 PM		Max. Marks: 60
Instructions:	<ul><li>1) All questions are compulsor</li><li>2) Figures to the right indicate</li></ul>		
,	oose correct alternative.  A mutex  a) Is a binary mutex  b) Must be accessed from onl c) Can be accessed from mul d) None of these	-	08
2)	Round robin scheduling falls up a) Non-preemptive scheduling b) Preemptive scheduling c) All of the mentioned d) None of the mentioned		·
3)	Which of the following is a part a) Memory c) ISR	of RTOS kernel? b) Input d) Register	
4)	The API stands for  a) Application Programming In b) Application Process Interfactor Application Programming In d) None of these	ce	
5)	Mailbox is a kernel object used a) Serial c) Parallel	l for communi b) Intertask d) Full duplex	cation.
6)	The two kinds of semaphores and a) mutex & counting counting & decimal	b) binary & counting	_
7)	A task is said to be in a) Running c) Ready to Run	state, if it is waiting for b) Waiting d) None of these	another event.

		<ul> <li>8) What is FIFO algorithm?</li> <li>a) first executes the job that came in last in the queue</li> <li>b) first executes the job that came in first in the queue</li> <li>c) first executes the job that needs minimal processor</li> <li>d) first executes the job that has maximum processor needs</li> </ul>	
	B)	<ol> <li>State True or False.</li> <li>Real time systems must have preemptive kernels.</li> <li>Time duration required for scheduling dispatcher to stop one process and start another is known as process latency.</li> <li>Event register is a Kernel object to indicate the occurrence of an event to a task.</li> <li>Operating system is a system software and hardware.</li> </ol>	04
Q.2	Ans a) b) c) d) e) f) g) h)	What do you mean by RTLinux Kernel? Write Characteristics of Real-Time operation system. Draw AVR ATmega8L microcontroller based embedded systems for Measurement of temperature. State application of embedded system. Define Real Time operating System (RTOS). Compare Hard and Soft Real Time Systems. Draw Clock circuit of AVR ATmega 8L. Define tasks and task states.	12
Q.3	Ans a) b) c) d)	wer the following. (Any Three) Write note on Counting semaphore. Discuss RTLinux Kernel in detail. Explain in detail characteristics of embedded system. Write a note on task and task structure.	12
Q.4	Ans a) b) c)	wer the following. (Any Two) Write Simple programs based on RTOS for LED interfacing. Write note on RTOS Kernel object; Messages. Explain the minimum component requirement of embedded system Design.	12
Q.5	Ans a) b) c)	bwer the following. (Any Two)  Design AVR ATmega8L microcontroller based embedded system for Measurement of Humidity.  Explain in detail round robin and FIFO scheduling.  Write note on Concept of mutex.	12

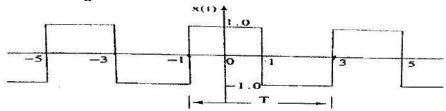
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# M.Sc. (Electronics) (Sem - II) (New) (NEP CBCS) Examination:

		March/Apr Signals and Syste			
		e: Tuesday, 20 May 2025 O AM To 01:30 PM		Max. Marks	s: 60
Instr	uction	ns: 1) All questions are compulsor 2) Figure to right indicate full r	-		
Q.1	A)	Choose correct alternative.			08
	1)	In the time scaling operation the as  a) amplification of the signal b) attenuation of the signal c) compression of the signal d) expansion of the signal	down	scaling signal is also known	
	2)	The I/O characteristics of shifting. a) Time invariant c) linear	-	m are independent of the time  Time variant  non-linear	
	3)	a) A new signal c) Impulse		th an impulse. Signal itself Signal multiplied by impulse	
	4)	The type of systems which are continuous quantized at certain levels are can also also also continuous			
	5)	Index of an array in MATLAB sta a) 0 c) Depends on the class of arr	b	) 1	
	6)	is not associated with the convolution. a) Folding Operation c) Multiplication Operation	b) d)	Shifting Operation	
	7)	The impulse response of discrete h [n] = u [n+3] The system is a) Causal c) Insufficient information	 b)	signal is given by  Non-causal  The system cannot be classif	ied

	8)	For an LTI discrete system to be stable, the square sum of the impulse response should be  a) Integral multiple of 2pi b) Infinity c) Finite d) Zero	
	<b>B)</b> 1)	State true or false.  The range of frequency spectrum for DTFS is $-\pi$ to $+\pi$ .	04
	2)	For existence of Fourier series, the function x(t) have infinite	
	2	number of discontinuities.	
	3)	<ul> <li>The condition of periodicity for a continuous time signal is</li> <li>x(t) = x(t +T<sub>0</sub>)</li> </ul>	
	4)		
Q.2	Ansv	ver the following (Any Six)	12
	-	What are the applications of MATLAB?	
	-	What is signal processing?	
		Explain unit step function.  Write the statement for the linearity property of the system.	
	-	Distinguish between continuous time and discrete time signal.	
	f)	What is window?	
	•	Write operations of the systems.	
	h)	Write a note on deterministic and random signal.	
Q.3		ver the following. (Any Three)	12
		Determine y(n)=cos x(n), system is linear or not.	
	b)	To represent Fourier series justify the functions with half-wave symmetry have only odd harmonics.	
	,	Write a note on MATLAB windows	
	d)	Sketch a DT signal $x(n)=2^{-n}$ for $-2 < n < 2$ obtain $y_2(n)=x(n).u(2-n)$	
Q.4		ver the following. (Any Two)	
	a)	Define a Signal. Explain the different methods to represent a DT signals.	12
	b)	Explain tabulation method of linear convolution. Compute the convolution $y(n)=x(n)^*h(n)$ where	
		$x(n)=\{1,1,0,1,1\}$ and $h(n)=\{1,-2,-3,4\}$ using tabulation method.	
	c)	State and prove linear convolution sum.	
Q.5		ver the following. (Any Two)	12
	a) b)	Explain folding and advance operations of the signals. Prove and explain graphically the difference between relations $x(n)^*\delta(n-n_0)=x(n-n_0)$	

c) Find the trigonometric Fourier series for the periodic signal x(t) is shown in figure.



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# M.Sc. (Electronics) (Sem - III) (New) (NEP CBCS) Examination: March/April - 2025 Digital Signal Processing (23131301)

	Digital Sig	ınal Processing	(23131301)
•	Thursday, 15-May-2 AM To 01:30 PM	025	Max. Marks: 60
Instruction	s: 1) All questions are 2) Figures to the r		arks.
•	Choose correct alter  The example of or  a) Ac power supp  b) Speech signal  c) Variation of roo  d) All of the ment	ne-dimensional sigr oly signal om temperature	<b>08</b> nal is
2	<ul> <li>The ROC of z-transis</li> <li>a) z=0</li> <li>b) z=∞</li> <li>c) Entire z-plane,</li> <li>d) Entire z-plane,</li> </ul>	except at z=∞	ition anti-causal sequence
3	<ul><li>Final value theores</li><li>a) All type of syst</li><li>c) Unstable syste</li></ul>		Stable systems
4	) The DFT of delays a) $e^{-j^2\pi ikn^0/N}$ c) $e^{j\pi ikn^0/N}$	b)	$(n-n0)$ is $e^{j^2\pi ikn} {^0/_N} e^{-j\pi ikn} {^0/_N}$
5	) If x(t) is odd then > a) Imaginary & ev c) Real & odd		Imaginary & odd Real & even
6	) In order to convert signal should a) Sampling c) Integrating		signal to a discrete-time  Differentiating  None of the mentioned

	′)	statement in the z-domain.  a) Entirely outside the unit circle  z =1  b) Partially outside the unit circle  z =1  c) Partially inside the unit circle  z =1  d) Entirely inside the unit circle  z =1	
	8)	method is used for Implementing a FIR system.  a) Direct form b) Cascade form  c) Lattice structure d) None of the mentioned	
B)			04
a) b) c) d) e) f)	Def Wh Def Wh Sta Wh Def	fine of Bilinear transformation filter.  Plat is mean by sampling? State the sampling theorem.  Plat is mean by sampling? State the sampling theorem.  Plat are the applications of digital signal processing?  Plat is the properties of z transform.  Plat is z transform? List the properties of z transform.	12
	Obt Find Def	tain IZT using residue method from $X(Z)=Z(Z+1)/(Z-1)^2$ d the Fourier transform of complex and real functions. fine and prove ZT of unit ramp function and comment on its ROC.	12
a)	Fir i) ii) Sta An teo	nd the FT of sgn(t) u(t) ate and Prove linearity property of DFT. an analog filter has the transfer function H(s)= 1/s+1 using BLT chnique determine the transfer function of digital filter H(Z) and	12
	Ans a) b) c) d) Ans a) b)	Answer a) Def b) Wh c) Def d) Wh e) Sta f) Wh g) Def h) Exp Answer a) Obt b) Find c) Def d) Wri Answer a) Find c) Def c) Def d) Wri c) Answer a) Find c) Def d) Wri e) Def d) Wri e) Def d) Wri e) Def e e) Def e e e e e e e e e e e e e e e e e e	statement in the z-domain. a) Entirely outside the unit circle  z =1 b) Partially outside the unit circle  z =1 c) Partially inside the unit circle  z =1 d) Entirely inside the unit circle  z =1 d) Entirely inside the unit circle  z =1 8) method is used for Implementing a FIR system. a) Direct form b) Cascade form c) Lattice structure d) None of the mentioned  B) State True or False. 1) The FT of real valued time signal has no symmetry. 2) The multiplication of two DFTs is equivalent to the circular convolution of their sequences in time domain. 3) FIR filters are recursive and they adopt any feedback. 4) Interpolation has to be performed in sampling rate conversion by rational factor.  Answer the following (Any Six). a) Define of Bilinear transformation filter. b) What is mean by sampling? State the sampling theorem. c) Define Kaiser Window. d) What are the applications of digital signal processing? e) State final value theorem. f) What is z transform? List the Properties of z transform. g) Define Nyquist rate. h) Explain existence of FT.  Answer the following (Any Three). a) Obtain IZT using residue method from X(Z)= Z(Z+1)/(Z-1)² b) Find the Fourier transform of complex and real functions. c) Define and prove ZT of unit ramp function and comment on its ROC. d) Write a note on PFE method.  Answer the following (Any Two). a) Find the FT of i) sgn(t) ii) u(t) b) State and Prove linearity property of DFT.

### Q.5 Answer the following (Any Two).

12

- a) Prove that stability criteria for LSI systems in terms of unit impulse response.
- **b)** Compute the eight-point DFT of a sequence.  $x(n)=\{1/2,1/2,1/2,0,0,0,0\}$  using in place radix-2 decimation in time FFT algorithm.
- **c)** State unilateral Z-transform. Prove shifting property of unilateral ZT using time advance function.

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## M.Sc. (Electronics) (Sem - III) (New) (NEP CBCS) Examination:

		A	March/Apri RM Microcontroller and Sy		
-			aturday, 17-May-2025 M To 01:30 PM		Max. Marks: 60
Instr	uction		<ol> <li>All questions are compulsor</li> <li>Figures to the right indicate</li> </ol>		narks.
Q.1	A) 1)	a)	ect the correct alternative. In LPC 2148 PLL setting time 100 μs 20 μs	is b) d)	
	2)	a)	In LPC 2148, ADC0 has	chanı b) d)	nels. 6 8
	3)	a)	To increase the code density A 64 bit instruction set Thumb 16 bit instruction set	b)	Jazzale 32-bit instruction set
	4)	,	In LPC 2148, when internal respectively begins executing at Address 0 Address 5	set is b) d)	removed the processor  Address 1  Address 7
	5)	a)	The Cache is placed between Flash memory and registers Peripherals		main memory and core none of these
	6)	a) c)		M is <sub>-</sub> b) d)	1-16KB 8-40KB
	7)	a) c)	in the address register and bro	_	enerate an address to be held ast on the <i>Address</i> bus.  Load and store  MOV
	8)	a) c)	What are the values of the I ar Register on reset? I=0, F=0 I=0,F=1	nd F b b) d)	oits in the Program Status I-1,F=1 I=1,f=0

	B)	<ul> <li>Write true/false:</li> <li>a) Abort mode generally enters when low priority interrupt is raised.</li> <li>b) ALL inputs in ARM are conditionally executed.</li> <li>c) The cpsr has two interrupt mask bits, 7 and 6 (or I and F), which control the masking of IRQ and FIQ, respectively.</li> <li>d) 32 bit CISC processor used by ARM 7</li> </ul>	04
Q.2	a) b) c) d) e) f)	What is ARM processor? Give its applications.	12
Q.3	a)	Write a note on UART used for LPC 2148. Explain Jazzele instruction set.	12
Q.4	a)	wer the following (Any Two) Write embedded c program to interface Relay to ARM microprocessor with suitable diagram. Explain in brief ARM bus architecture. Give the functions of following registers in ARM processor  1) Stack Pinter 2) Link registers 3) Program counter	12
Q.5	a)	wer the following (Any Two) What is barrel shifter? How does it increase the speed of execution in ARM processor. Draw the format of program status register in ARM processor. Explain different bits in it. Explain with example Arithmetic and Logical, instruction in ARM.	12

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No.	Set	

# M.Sc. (Electronics) (Sem - III) (New) (NEP CBCS) Examination:

			March/Ap Advanced Digital Design		
-			Monday, 19-May-2025 AM To 01:30 PM		Max. Marks: 60
Inst	ructio	ons:	<ul><li>1) All questions are compuls</li><li>2) Figures to the right indicate</li></ul>	-	narks.
Q.1	A)		noose correct alternative. In case of VHDL, '<=' assign a) signal c) constant	ment o b) d)	<b>08</b> perator definesvalue. variable high impedance
		2)	Which of the following technology SRAM c) Flash	b)	s used for PLD programming? EPROM All of these
		3)	The main purpose of HDL is a) analog c) both a & b		gn circuits. digital mixed technology
		4)	In case of VHDL, by which c accessed? a) library c) type	lause th b) d)	ne package std_logic_1164 is use both a & b
		5)	In case of Data Types STD_is a) low c) weak 0	LOGIC b) d)	_1164 the meaning of 'L'  0 all of these
		6)	In which level design of EDA a) back end c) both a & b		and route are included? front end mixed end
		7)	In case of LOOP statement, allowed? a) outside c) both a & b	where b) d)	exit and next statements are inside none of these
		8)	In which type of category, the a) Sequential c) Process	b)	

04

	,	<ol> <li>The NAND operator and NOR operator are not associative operator.</li> <li>The addition operator used in VHDL code is '&amp;' operator.</li> <li>The data information regarding a data vector is return by signal attributes.</li> <li>The statement PROCESS is always concurrent statement.</li> </ol>	S.
Q.2	Ans a) b) c) d) e) f) g) h)	wer the following. (Any Six)  Explain the role of Library in VHDL.  Give the advantages of VHDL.  What is PAL device.  Give the difference between CPLD and FPGA.  Give the syntax of Process statement.  Write entity for AND gate.  Write the names of sequential statement for VHDL.  Write entity for 4:1 multiplexer.	12
Q.3	Ans a) b) c) d)	wer the following. (Any Three) Illustrate the Entity using full adder for VHDL design. Explain the LOOP statement in VHDL? Explain the Attributes and Generic. In case of PLD discuss architecture of FPGA.	12
Q.4	Ans a) b) c)	wer the following. (Any Two) Explain the various language element of VHDL and Explain two operators in detail. Explain the EDA tools. Write a note on Macrocell. Give VHDL code for 8-bit input comparator.	12
Q.5	Ans a) b) c)	wer the following. (Any Two) State and Explain the role of various types of architecture bodies in VHDL using suitable example. What do you mean PLD devices. Discuss architecture of PAL & PLA. Give VHDL code for 8:1 demultiplexer.	12

B) State True or False.

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# M.Sc. (Electronics) (Sem - III) (Old) (CBCS) Examination: March/April - 2025 Digital Signal Processing (MSC21301)

		Digital Signal Pro	ocessing (		
-		e: Thursday, 15-May-2025 O AM To 02:00 PM		Max. Marks	s: 80
Inst	ructior	ns: 1) Q.Nos.1 and 2 are com 2) Attempt any three ques 3) Figures to the right indi	stions from (		
Q.1	•	Choose correct alternative Which of the following is a m a) Direct form c) Lattice structure	nethod for Ir b)	mplementing an FIR system? Cascade form All of the mentioned	10
	2)	The changing or analyzing in discrete sequences of numb a) Discrete Fourier Trans c) Digital Signal Process	ers is called sform b)	d as Sampling	
	3)	What is the ROC of z-transferal Z=0 b) Z=∞ c) Entire z-plane, excepted Entire z-plane, excepted	at z=∞	duration causal sequence?	
	4)	The ROC of the Z-transform a) Zero c) One	b)	nal cannot contain Poles None of the mentioned	
	5)	If $x(n)$ is causal sequence the a) $x(0) = \lim_{z \to 0} X(z)$ b) $x(0) = \lim_{z \to \infty} X(z)$ c) $x(\infty) = \lim_{z \to 1} X(z)$ d) $x(\infty) = \lim_{z \to 1} X(z)$	) Z) Z)		
	6)	The FT does not exist for all a) Periodic c) Symmetric	b)	ions. Aperiodic Cyclic	
	7)	Inverse Z transform by power division method.  a) Direct c) Long	er series ex b) d)	pansion is also called as Indirect Both a and c	

	·	interchange the input and output in the flow graph, then the resulting structure is called as	
		a) Direct form-I b) Direct form-II	
		c) Transposed form d) None of the mentioned	
	9)	Which of the following should be done in order to convert a continuous time signal to a discrete-time signal?  a) Sampling b) Differentiating c) Integrating d) None of the mentioned	
	10)	In bilinear transformation, the left-half s-plane is mapped to statement in the z-domain.  a) Entirely outside the unit circle  z =1 b) Partially outside the unit circle  z =1 c) Partially inside the unit circle  z =1 d) Entirely inside the unit circle  z =1	
	B)	<ol> <li>State true or false.</li> <li>The function given by the equation x (n) =1. for n=0; x (n) =0, for n≠0 is a unit step function.</li> <li>FIR filters are non-recursive and do not adopt any feedback.</li> <li>If x(n) is real then X*(ω) = X(-ω)</li> <li>If the discrete time LTI system is BIBO stable Entire z-plane, except at z=∞ is the ROC of the system function H (z).</li> <li>Continuous time non-periodic signal have aperiodic continuous spectra.</li> <li>The multiplication of two DFTs is equivalent to the circular convolution of their sequences in time domain.</li> </ol>	06
Q.2	Answ a) b) c) d)	ver the following question Find the FT of the signal $x(t) = \cos(\omega 0t)$ . Write a note on quantization with A/D conversion. What is DSP? What are the applications of DSP? Write a note on Bilinear transform filter.	16
Q.3	a)	·	08
	b)	ROC. Draw flow diagram of DITFFT for N= 16.	08
Q.4	a)	'	10
	b)	convolution of their sequences in time domain.  Obtain IZT using residue method from X (Z)= Z(Z+1)/(Z-1) <sup>2</sup>	06
	- ,		-

8) If we reverse the directions of all branch transmittances and

### SLR-ZJ-14

Q.5	a)	Determine 2-point and 4-point DFT of a sequence $x(n) = u(n) - u(n-2)$ sketch the magnitude of DFT in both cases.	80
	b)	What is Kaiser Window? Explain the procedure for designing an FIR filter using the Kaiser window.	80
Q.6	a)	An analog filter has the transfer function H(s)= 1/s+1 using BLT technique determine the transfer function of digital filter H(Z) and also write the difference equation of digital filter.	80
	b)	Prove that ideal filters are practically not realizable.	08
Q.7	a)	Determine direct form-II realization for each of the following LTI system i) $2y(n) + y(n-1) - 4y(n-3) = x(n) + 3x(n-1)$ ii) $y(n) = x(n) - x(n-1) + 2x(n-2) - 3x(n-4)$	10
	b)	State and prove Initial Value Theorem.	06

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P

# M.Sc. (Electronics) (Sem - III) (Old) (CBCS) Examination: March/April - 2025 Advanced Digital Design with VHDL(MSC21302)

-		e: Saturday, 17-May-2025 Max. Marks: D AM To 02:00 PM	80
Instr	uction	ns: 1) Q.1 and Q.2 are compulsory. 2) attempt any three questions from Q.3 to Q.7. 3) Figure to right indicate full marks.	
Q.1	A)	Choose correct alternative.	10
	1)	PLA is used to implement  a) A complex sequential circuit  b) A simple sequential circuit  c) A complex combinational circuit  d) A simple combination circuit	
	2)	Configurable logic blocks in FPGA are based on  a) Look up tables b) Programmable Interconnect c) Carry look ahead logic d) None of the above	
	3)	SIGNED and UNSIGNED data types are defined in  a) Std_logic _1164 package b) Std_logic package  c) Std_logic_arith package d) standard package	
	4)	If a and b are two STD_LOGIC_VECTOR input signals, then legal assignment for a and b is  a) x<=a.b b) x <= a OR b c) x <= a +b d) x <= a && b	
	5)	The FPGA architecture has based on to generate logic functions.  a) LUT b) Multiplexer c) Macrocell d) Both a & b	
	6)	The back-end design is used to create source of design.  a) Technology b) Physical c) Logic d) circuit	
	7)	The Is one of the ways of design entry in the CAD process.  a) HDL b) VHDL  c) Verilog d) All of the mentioned	

- **8)** Synonym of JTAG is \_\_\_\_\_.
  - a) Joint Test Action Group

		<ul><li>b) Joint Test Action Goal</li><li>c) Joint Test Application Group</li><li>d) Joint Test Application Goal</li></ul>				
	9)	In VHDL there are types of shift operators. a) Three b) Four c) Five d) Six				
	10)	Use of constant is to  a) Represent default value b) Represent local information c) Represent wires d) Pass value between entities				
	2) 3) 4) 5)	methodology. The SRAM are the programming technologies used for PLD. The front end design is used to create logic source of design.	06			
Q.2	a) b)	er the following:  Explain the architecture of FPGA.  Explain the advantages of PLD devices.  Explain the syntax of Process statement.  Explain the syntax of the LOOP statement.	16			
Q.3	•	What do you mean Attributes and Generic. Explain it with suitable example. Write a note on PLA. Explain architecture of PLD's.	08			
Q.4	a) b)	State and explain the role of various types of architecture bodies in VHDL using suitable example. Write VHDL code for 8-bit input comparator.				
Q.5	a) b)	Explain the SPLD in detail with suitable diagram. Write VHDL code for ALU.	08 08			
Q.6	a) b)	Describe the operators in the VHDL. Explain the architecture of CPLD. Write VHDL code for 1:8 Dmux using behavioral modeling.	08			
Q.7	a) b)	Explain the EDA tools. Write a note on Macrocell. Write VHDL code for D flip flop using wait statement.	10 06			
Q.7	•					

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No.	Set	

# M.Sc. (Electronics) (Sem - III) (Old) (CBCS) Examination: March/April - 2025 ARM Microcontroller and System Design (MSC21306)

		Α	RM M	icrocontroll	er and Sys	tem	Des	ign (M	SC21	306)	
•			•	/, 19-May-20 02:00 PM	25					Max. Mark	ks: 80
Inst	ructio	ons:	2) Atte	los.1 and 2 a empt any thre gures to the ri	e questions	from			.no.7		
Q.1	A)	Select the correct alternative.  1) What is the significance of "!" in a load/store instruction a) Don't update base register in post-indexed load/sto b) Don't update base register in pre-indexed load/store c) Update base register in post-indexed load/store d) Update base register in pre-indexed load/store					ore	10			
		2)	a) 10	C 2148. I <sup>2</sup> C b 00 Kbit/S 00 Kbit/S	us supports	bit ra b) d)	200	pto Kbit/S Kbit/S		<u>.</u> .	
		3)	The L a) 24 c) 6		quipped with ata exchange						es
		4)	Mask a) By b) Ro c) Tr ot	C 2148, which register? It addressate addressate addressate addressate action to A reating sets of the above	oility .RM local bu f port bits in	s for	faste	st poss	ible I/C	) timing	)
		5)	Thum a) 2 c) 8	b instruction	set executes	b) d)	4 16	bit instr	uction	S.	
		6)	<ul><li>a) Th</li><li>b) Ja</li><li>c) 64</li></ul>	crease the conumb 16 bit in Ezzale 32 bit in bit in the bit instruction one of these	nstruction se nstruction se	t	uses <sub>-</sub>				

		7)	a) b) c)	e synonym of AMBA is ARM Microcontroller Bus A ARM Micro-Bus Architectur Advanced Microcontroller E Advanced Micro-Bus Archit	rchite e Bus A	rchitecture	
		8)	exe a)	LPC 2148, when internal resecuting at address 0 address 5	b)	removed the processor begins address 1 address 7	
		9)	a) b) c)	e Cache is placed between get Flash memory and registers Main memory and core Peripherals none of these			
		10)	use a)	•	b)		•
	B)	1) 2) 3) 4)	In I Wh pro LP Us To ins	whether true or false.  LPC 2148 on chip static RAMen subroutine is called processory counter.  C 2148 has three timers I counter mode is non-privileged move from an ARM register truction is used.  e nature of instruction size in	esso unte iode. to a	s-40KB. r stores return address in r. status register MOV	06
Q.2	Wri a) b) c) d)	Ex Giv Wr	plair ve a rite a	notes on. In I <sup>2</sup> C bus controllers of LPC dvanced features of ARM properties on watchdog timer. The block diagram of ARM m	oces	sor.	16
Q.3	Ansa)	swer the following.  What is barrel shifter? How does it increase the speed of execution in ARM processor.  Explain the memory system of the ARM processor.				16	
Q.4	Ans a) b)	Wł Wł	nat r	e following. neat labeled block diagram of do you mean by interrupt? Estages.		be AMBA bus architecture.	16

16

	a)	Explain the design of ARM LPC 2148 microcontroller based system for humidity measurement with suitable interfacing diagram.	
	b)	Explain the following instructions.	
	•	1) MOV R1,R2,LSL #2	
		2) LDR R0, [R1]	
		3) RSB R3,R3,R3,LSL #3	
		4) MUL R0,R1,R2	
Q.6	Ans	wer the following.	16
	a)	Interface LED and switch to ARM microprocessor and write embedded c program when switch press LED is ON.	
	b)	Explain the functions of Stack Pointer and Program counter of ARM processor.	
Q.7	Ans	wer the following.	16
	a)	Explain ADC of ARM LPC 2148 in detail.	
	b)	Write a note on Thumb instruction and Jazzele instruction set.	

Q.5 Answer the following.

Seat	Sat	D
No.	Set	

# M.Sc. (Flectronics) (Sem - IV) (New) (CBCS) Examination:

		IVI.C	•	March/April working and Data Comm	- 20	<b>25</b>
-				esday, 14-May-2025 o 02:30 PM		Max. Marks: 60
Instr	ucti	ons:		Il questions are compulsory igures to right indicate full m		
Q.1	A)		A Blu a)	correct alternative. uetooth device is limited to a 1m 10m		<b>08</b> ge of 5m 20m
		2)	a)	TTP request message alway body header	ys co b) d)	
		3)	a)	security at network layer is p TCP SCTP	b) d)	ded by IPsec UDP
		4)	chan a)	communication mode use inel in both directions. simplex mode Full duplex mode	b)	half duplex mode
		5)	a)	_ is not a guided transmissi Free space twisted pair cable		fiber optic cable
		6)	,	_ of the following is a digita FDM TD	l mul b) d)	tiplexing technique. WDM both a and b
		7)		uses 2.4 GHz ISM ba Bluetooth I <sup>2</sup> C	and. b) d)	Wi-Fi None of these
		8)	a)	W stands for Wide Web Wavelength World Wide Wave	b) d)	World Wide Web Wide Web World

	B)	Write True/False.	04
	-	1) Standard Ethernet provides data rate of 20 Mbps.	
		Data framing is not a responsibility of the data link layer of the	
		2) OSI model.	
		3) Image is not the type of data representation.	
		4) Simplest protocol does not provide error and flow control.	
Q.2	Ans	swer the following. (Any Six)	12
·	a)	Explain the need and types of IP Address.	
	b)	Explain components of data communication.	
	c)	Draw signal for sequence 010010 using AMI technique.	
	d)	Explain in detail the physical layer of OSI model.	
	e)	Write a note on Bluetooth technology.	
	f)	Explain Digital Subscriber Line (DSL).	
	g)	Give any four differences in between FTP and HTTP.	
	h)	Write a note on Cryptography.	
	•		
Q.3	Ans	swer the following. (Any Three)	12
	a)	Explain the domain name system.	
	b)	Explain IPV6 addressing.	
	c)	Write a note on stop and wait ARQ protocol.	
	d)	Explain Architecture of WWW.	
Q.4	Δno	swer the following. (Any Two)	12
<b>Q.</b> -T	a)	Explain SONET Network.	12
	b)	Describe DNS in the internet.	
	c)	Explain the concept of UDP and TCP.	
	Ο,	Explain the concept of CD. and TOT.	
Q.5	Ans	swer the following. (Any Two)	12
	a)	Explain Internet Protocols for Internetworking.	
	b)	What is mean by Network? Explain categories of Network.	
	c)	Write a note on SMTP and HTMP.	

Seat	Sat	D
No.	Set	Γ

# M.Sc. (Electronics) (Sem - IV) (New) (CBCS) Examination:

			March/A Mechatronics and Industr	•		
•			Friday, 16-May-2025 PM To 05:30 PM		Max. Mark	s: 60
Instr	ructio	ons:	<ol> <li>All questions are compuls</li> <li>Figures to the right indicate</li> </ol>	•	narks.	
Q.1	A)		An internal relay in a PLC do is used for  a) Redundancy c) Delays	oes not	control a physical device, but Internal logic Manual override	08
		2)	Ladder logic programming of a) Logic gate symbols with b) Virtual relay contacts and c) Function blocks with cord) Text-based code Hierog	connected coils	eting lines	
		3)	The primary goal of mechat a) Size c) Performance	ronics is b) d)	Packaging	
		4)	PLCs are typically programma) Ladder c) Mathematical	b)	ng logic. Boolean C++	
		5)	The full form of SCADA is _ a) Supervisory Control and b) Supervisory Control and c) Supervisory Column and d) None of the above	l Docum l Data A	cquisition	
		6)	The output coil in ladder log a) Operator c) Actuator	ic repre b) d)	sents the control of an Alarm only Equation	
		7)	The CPU of the PLC execut operations.  a) Arithmetic and logic c) Painting and welding	b)	user program and performs Graphical and drawing Timing only	

		a) Network b) Remote field c) Virtual d) Cloud-based	ices.
	B)	<ul> <li>State true or false.</li> <li>1) The Boolean expression is not used for PLC programming.</li> <li>2) Solenoids, lamps, motors are connected to Digital output.</li> <li>3) RTU stands for Remote Transfer Unit.</li> <li>4) The +5Volt is nominal DC voltage given to PLC.</li> </ul>	04
Q.2	a) b) c) d) e) f)	Draw structure of RTU. Write note on PLC's instructions Write note on Modbus. Write note on standard Symbols. Explain Components of the PLC. Draw Basic architecture of DCS. Define Centralized Control system (CCS). Explain Memory.	12
Q.3	a) b) c)	Write note on PLC Devices. Write note on Counter functions. Explain Concept of industrial automation. Compare DCS and CCS.	12
Q.4	a) b)	Explain SCADA Architecture in detail.  Compare Open and closed loop systems.  Write Ladder program to turn on motor after 05 minute.	12
Q.5	Ans a) b) c)	swer the following question (Any Two)  Explain Master Control relay with suitable example.  Write note on Boolean algebra programming.  Design of Ladder diagrams for process control with suitable example	<b>12</b>

Seat	Sat	D
No.	Set	F

## M.Sc. (Electronics) (Sem - IV) (New) (CBCS) Examination: March/April - 2025 Microwave Devices, Antennas and Measurements (23131406)

microwave bevices, Americas and measurements	23131700 <i>)</i>

				(=0.01.100)		
Day Time	Max. Marks: 6	C				
Insti	ructior	<b>is:</b> 1) All Questions are compulso 2) Figure to right indicate full r	-			
Q.1	A)	Choose correct alternative.	0	8		
	1)	Attenuation of a propagating wave is due to  a) Conductor loss b) Di-electric loss c) Sum of both conductor loss and di electric loss d) Attenuation is different from the losses				
	2)	is a single cavity klystron by using a reflector electrode after a) Backward wave oscillator c) Travelling wave tube	er the b)	cavity Reflex klystron		
	3)	Scattering matrix for a reciprocal a) Symmetric c) Skew symmetric	b)	ork is Unitary Identity matrix		
	4)	The Gauss law employstl density? a) Green theorem c) Gauss theorem	b)	m for the calculation of charge Stokes theorem Maxwell equation		
	5)	is a device that converts a a) Microwave tube c) Photon amplifier	electro b) d)			
	6)	GaAs is used in fabricating Gunn diode. Gunn diode is a) bulk device b) sliced device c) made of different type of semiconductor layers d) none of these				
	7)	Maxwell's equation for electroma a) $\nabla xE = -j\omega\mu$ (vector H) c) $\nabla xH = -j\omega\mu$ (vector H)	_	c waves in a waveguide is $ \nabla xE = -j\omega\mu \text{ (vector E)} $ $ \nabla xH = -j\omega\mu \text{ (vector H)} $		

	8)	<ul><li>Silicon and germanium are called</li><li>a) direct gap</li><li>c) band gap</li></ul>	b) d)	semiconductor indirect gap indirect band gap	
	,	State true or false.  The electrodes of a Gunn diode  The dominant mode in the TM w  The first Maxwell law is based o	are ma aves is n Farac	ade of molybdenum. sTM <sub>20</sub> day and Lenz law.	04
Q.2	a) b) c) d) e) f)	ver the following: (Any Six) Explain Modes in waveguides. What is Rat-Race junction? Write a note on TE and TM mode Sate properties of S-matrix. What is tee? Mention types of it. Explain rectangular waveguide. Define isolators. State boundary conditions.	S.		12
Q.3	a) b) c)	ver the following. (Any Three) Write a note on Lossy dielectric metaplain Co-axial connectors. Explain waveguide. What are the Write a note on characteristics im	feature	es of waveguide?	12
Q.4	a)	ver the following. (Any Two)Write a note on Smith chart. CalcRn circle.Explain Shunt Tee.A transmission line has followingG= 0.5 m ℧/m, F=1GHz, L=8nH/ma) Characteristics impedanceb) Propagation constant	parame	eters R= 2Ωm,	12
Q.5	a) b)	ver the following. (Any Two) Explain double stub matching me Discuss Slot antenna and Microst Derive the wave equation for TE a	rip Ant		12

Seat	Sat	D
No.	Set	

## M.Sc. (Electronics) (Sem - IV) (New/Old) (CBCS) Examination: March/April - 2025

	M	icro	wave Device	March/Apr s, Antennas an		25 asurements (MS	SC21401)	
			Wednesday, 1 PM To 06:00 P				Max. Marks:	: 80
Inst	ructi	ons	2) Attempt ar	and 2 are compul ny three questions right indicate full	s from	Q. No. 3 to Q. No.	. 7.	
Q.1	A)		<ul><li>a) sliced de</li><li>b) bulk devi</li></ul>	in fabricating Gui vice ce different type of s		de. Gunn diode is nductor layers		10
		2)	ratio is a) 1 b) 0 c) Infinity			the value of standi R	ng wave	
		3)	a) Electric fi	eld intensity	b)	ectromagnetic theo Electric flux dens Magnetic flux der	sity	
		4)	a) Antenna	vice that converts mplifier	b)	rons to photons or Electron gun Microwave tube	vice-versa.	
		5)	<ul><li>a) E is para</li><li>b) H is para</li></ul>	llel to wave direct sverse to wave di	ion			
		6)	Scattering ma a) Symmetr c) Skew syr		b)	vork is Unitary Identity matrix		
		7)	The Gauss la charge densit a) Green th c) Maxwell	y. eorem	b)	em for the calculat Stokes theorem Gauss theorem	tion of	

		8)	_	•	ectromagne	elic waves in a waveguide	
				$\nabla \times \mathbf{E} = -j\omega\mu$ (vector		$\nabla \times E = -j\omega\mu(\text{vector E})$ $\nabla \times H = j\omega\mu(\text{vector H})$	
		9)	,	is not an Omni-dire Half-wave dipole Discone	ectional an b) d)	Marconi	
		10)	amp a)	klystron tube used in blifier. Crossed field Parallel field	a klystron b) d)		
	B)	Sta 1) 2) 3) 4) 5)	A m Stri In a heli A h pro Pov rad The	p lines are not a type a backward wave osci ix from the collector to ollow rectangular way pagation.  Wer radiated from an a liation intensity.	TEM line of lator, the lowards the veguide su	•	06
Q.2	An a) b) c) d)	Exp Wr Exp	plain ite a plain	following: Twists, bends, corne note on SWR. Circulators and Isola Microwave? What ar	tors.	ications of microwave?	16
Q.3	An a) b)	Wh the Wh	nat ar m.	re the Maxwell's equa		natching? Explain any one of plain with its boundary	08
Q.4	An a) b)	Wr	ite a	following. note on Rat Race Jur Klystrons and Multica	•	plain Directional Couplers. ron Amplifiers.	80 80
Q.5	An a)	Ex	plain		Derive the	expression for hyperbolic	10
	b)		ction	i. s Slot antenna and Mi	crostrip An	ntennas.	06

Q.6	<b>Answer</b>	the foll	lowina.
<b>~</b> :~	<i>,</i> ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		. • • • • • • • •

- a) Write a note on Cavity Resonator. Calculate Expression for f<sub>0</sub> in rectangular cavity resonator.
- b) Write a note on transmission line. Derive the transmission line equation.

#### Q.7 Answer the following.

- a) A certain transmission line has characteristics impedance is  $[75+j0.01\Omega]$  and is terminated in load impedance of  $[70+j50\Omega]$  compute
  - i) Reflection coefficient ( $\Gamma$ )
  - ii) Transmission coefficient (T)

iii) 
$$T^2 = \frac{Zl}{Zo} [1 - \Gamma_1^2]$$

b) Write a note on InP diode.

Seat	Cat	D
No.	Set	

	IVI.	.SC. (EI		iv) (New/Oi ch/April - 20	id) (CBCS) Examination:	
		Net			ations (MSC21402)	
•			ау, 16-Мау-2025 Го 06:00 РМ		Max. Marks: 80	1
Instr	uctio	2)	Q. Nos. 1 and 2 are of Attempt any three quality Figures to the right in	uestions from	Q. No. 3 to Q. No. 7. arks.	
Q.1	A) 1)				10 entire capacity of the channel in	1
		a)	rections. Simplex mode Both a and b	•	Half duplex mode Full duplex mode	
	2)	OSI mo	•		data link	
	3)	a)	prevents sig guard band amplifier	b)	ing in FDM. band pass filter low pass filter	
	4)	a) ¯	eld of an HDLC frame 011111110 01010101		10101010 11111111	
	5)	commu a)	L, channel 0 of the b inication. Upstream Voice	bandwidth is i b) d)	Downstream Idle	
	6)		ptic cable carries the voltage microwave	e signal in the b) d)	e form of current light	
	7)	service	-	es the interfa	ce to the user to use the e-mail	
			Transport Application	b) d)	Session Presentation	
	8)	a) c)	_ coding technique re Manchester NRZ-L	emoves the p b) d)	oroblem of baseline wandering. NRZ-I RZ	

	9)	<ul><li>is not a guided transmission</li><li>a) Free space</li></ul>	n me b)	dium. Fiber optic cable	
		c) Twisted pair cable	d)	Coaxial cable	
	10)	a) www c) Browser	fy an b) d)	y information over internet. HTTP URL	
	B)	<ol> <li>Write True/False.</li> <li>Network interfacing card of a I</li> <li>Noise means the signal loss in</li> <li>Image is not the type of data r</li> <li>Simplest protocol does not pro</li> <li>A BSS with AP is referred to a</li> <li>Star topology has Point-to-pointhe network.</li> </ol>	n data epres ovide s infr	a communication. sentation. error and flow control. rastructure network.	06
Q.2	a) b) c)	wer the following. Write a note on Cryptography. Explain the need and types of IP A Explain Digital Subscriber Line (DS Write a note on ATM technology.		SS.	16
Q.3	a)	wer the following.  Describe data transmission for ana  Explain in detail OSI & TCP/IP- Lay	_	•	16
Q.4	a)	wer the following. Explain in detail wired LAN Etherne Write a note on Routers and Gatev		es.	16
Q.5	a)	wer the following. Explain Bluetooth technology. Explain in detail Electronic Mail (SN	ЛТР)	and File Transfer.	16
Q.6	a)	wer the following. Discuss Network Security services Explain Internet Protocols for Intern		orking.	16
Q.7	a)	wer the following.  Explain the concept of UDP and TO  Write a note on SMTP and HTMP.	CP.		16

	T	1	
Seat		Cat	D
No.		Set	

# M.Sc. (Electronics) (Sem - IV) (New/Old) (CBCS) Examination:

			April - 2025 nics (MSC21403)	
•		e: Tuesday, 20-May-2025 0 PM To 06:00 PM	Max. Marks:	80
Insti	ructior	ns: 1) Q.1 and Q.2 are compul 2) attempt any three quest 3) Figure to right indicate f	ions from Q.3 to Q.7.	
Q.1	A)	Choose correct alternative.		10
	1)	<ul><li>If characteristics λ ≥ Lx, Ly a quantum</li><li>a) dot</li><li>c) well</li></ul>	and Lx Ly ≪Lz then it stands for b) wire d) bulk	
	2)	The triangular well wave fund of the potential well  a) neither symmetric or and b) symmetric  c) neither asymmetric or and d) antisymmetric		
	3)	The superlattice consists of a (MQW)  a) irregular c) periodic	b) regular d) none of these	
	4)	As device or feature size is reand more purely beginn a) classical effect c) nanoelectronics	educed towards a nanometer, more n to emerge. b) quantum effect d) all of these	
	5)	The hereto-junctions semicor compounds.  a) III-IV c) III-V	nductors are based on row b) IV-V d) IV-III	
	6)	The MBE technique is import system.  a) 2 c) 0	tant for fabrication of DEG b) 1 d) 3	

	7)	The operation of negative differential resistor (NDR) quantum well electron device is based on  a) quantum confined stark effect b) resonant tunnel effect c) both a and b d) none of these	
	8)	For parabolic well, the energy levels (En) are proportional to a) $n^{2/3}$ b) $n$ c) $n^2$ d) $n^{1/3}$	
	9)	The DOS for 2DEG system exhibits shaped energy dependence.  a) triangular b) parabolic c) line d) staircase	
	10)	The is the organic semiconductors  a) Poly Phenylene Vinylene (PPV)  b) Poly Flu Orene (PFO)  c) C-60  d) all of these	
	B) 1) 2) 3) 4) 5) 6)	well. The Coulomb Blockade voltage range is in between -e/2C and +e/2C The electron energies in the quantum well obtained for infinite well and finite well are do not differ too much. The quantum wire is effectively one dimensional electron gas system.	06
Q.2	Answ a) b) c)	ver the following:  Explain Split-Gate technique.  Explain the square quantum well of finite depth.  Explain the quantum wire and dot with respect to the characteristics length.  Discuss the limitations of microelectronics	16
Q.3	a) b)	Explain in detail Single Electron Transistor. Explain the modulation doped quantum wells	09 07
Q.4	a)	Explain in detail basic properties of two-dimensional semiconductor nanostructures.	10
	h)	Write a note on quantum dots	06

### SLR-ZJ-29

Q.5	a) b)	Explain the parabolic and triangular quantum well. Write a note on Multiple Quantum Well (MQW).	10 06
Q.6	a) b)	Explain the fabrication methods of nanomaterials. Explain in detail Heterojunctions semiconductors.	09 07
Q.7	a)	Explain the Resonant tunnelling effect and discuss the three terminal Resonant tunnelling devices.	10
	b)	Write a note on concept of superlattice.	06

Seat	Sat	D
No.	Set	

## M.Sc. (Electronics) (Sem - IV) (New/Old) (CBCS) Examination: March/April - 2025 Mechatronics and Industrial Automation (MSC21406)

	ľ	Mechatronics and Industr	ial A	utomation (MSC214	06)
-		Thursday, 22-May-2025 PM To 06:00 PM			Max. Marks: 80
Inst	ructions	<ul><li>: 1) Questions 1 and 2 are co</li><li>2) attempt any three from C</li><li>3) Figure to the right indicat</li></ul>	). No	. 3 to Q. No. 7.	
Q.1	<b>1)</b> 7 a)	ultiple choice questions: The mechatronic design proce One Two	ess co b) d)	onsists of phases Three Four	. 10
	a) b) c)	What is the difference betwee Both are same HMI is not related with SCA HMI can be a part of SCAD SCADA is a part of HMI	ΔDA		t of HMI
	a)	A PLC consists of Processor Unit Input/output Section	b) d)	•	
	a) c)	The acronym PLC stands for: Pressure Load Control Pneumatic Logic Capstan Pressure Loss Chamber	b)		Controller
	<b>5)</b> T a) c)		e in v b) d)	very little time. Installation All of the above	
	•	A single normally-closed co	series eries entact	es S	
				-	

	<ul> <li>8) In a PLC, the scan time refers to the amount of time in which</li> <li>a) the technician enters the program</li> <li>b) timers and counters are indexed by</li> <li>c) one "rung" of ladder logic takes to complete</li> <li>d) the entire program takes to execute</li> </ul>	
	<ul> <li>9) What is the full form of SCADA?</li> <li>a) Supervisory Control and Document Acquisition</li> <li>b) Supervisory Control and Data Acquisition</li> <li>c) Supervisory Column and Data Assessment</li> <li>d) Supervisory Column and Data Assessment</li> </ul>	
	<ul> <li>10) The difference between online and offline PLC programming is</li> <li>a) Whether the PLC is running or stopped</li> <li>b) Whether the programming PC has internet connectivity</li> <li>c) The type of programming cable used</li> <li>d) Where the edited program resides</li> </ul>	
	<ol> <li>State true or false:</li> <li>The graphic display of the whole plant provides a graphical and logical representation of the process.</li> <li>For PLC programming PICPGM is used.</li> <li>Normally open contacts are open when Input is not energized</li> <li>A open system is a collection of components that is designed to drive a given system with a given input to a desired output.</li> <li>Actuators produces motion or cause some action</li> <li>All block diagram languages consist of two fundamental objects: signal wires and blocks.</li> </ol>	06
Q.2	<ul> <li>Answer the following:</li> <li>a) Write note on Concept of industrial automation.</li> <li>b) Explain the architecture of RTU with suitable diagram</li> <li>c) Write note on registers.</li> <li>d) What do you mean by SCADA Protocols.</li> </ul>	16
Q.3	<ul><li>Answer the following:</li><li>a) Write Timer function of PLC in detail with suitable example.</li><li>b) Write note on Arithmetic functions.</li></ul>	10 06
Q.4	<ul> <li>Answer the following:</li> <li>a) Draw Ladder diagram program to ON-OFF the out device and its equivalent circuit diagram.</li> <li>b) What do you mean by design Process of mechatronics</li> </ul>	10 06

Q.5	Answer the following:					
	a)	Write note on DCS communication.	08			
	b)	Write not on system modeling.	80			
Q.6	Answer the following:					
	a)	What is SCADA? Explain types of SCADA in details.	10			
	b)	Explain in detail architecture of DCS	06			
Q.7	Answer the following:					
	a)	List the advantages and disadvantages of mechatronics systems.	10			
	b)	Explain the IO modules and their Characteristics.	06			